

PUSH-PULL FOUR CHANNEL DRIVERS

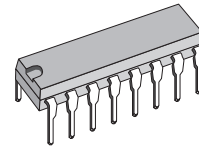
- OUTPUT CURRENT 1A PER CHANNEL
- PEAK OUTPUT CURRENT 2A PER CHANNEL (non repetitive)
- INHIBIT FACILITY
- HIGH NOISE IMMUNITY
- SEPARATE LOGIC SUPPLY
- OVERTEMPERATURE PROTECTION

DESCRIPTION

The L293B and L293E are quad push-pull drivers capable of delivering output currents to 1A per channel. Each channel is controlled by a TTL-compatible logic input and each pair of drivers (a full bridge) is equipped with an inhibit input which turns off all four transistors. A separate supply input is provided for the logic so that it may be run off a lower voltage to reduce dissipation.

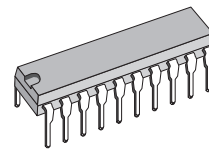
Additionally, the L293E has external connection of sensing resistors, for switchmode control.

The L293B and L293E are package in 16 and 20-pin plastic DIPs respectively ; both use the four center pins to conduct heat to the printed circuit board.



DIP16

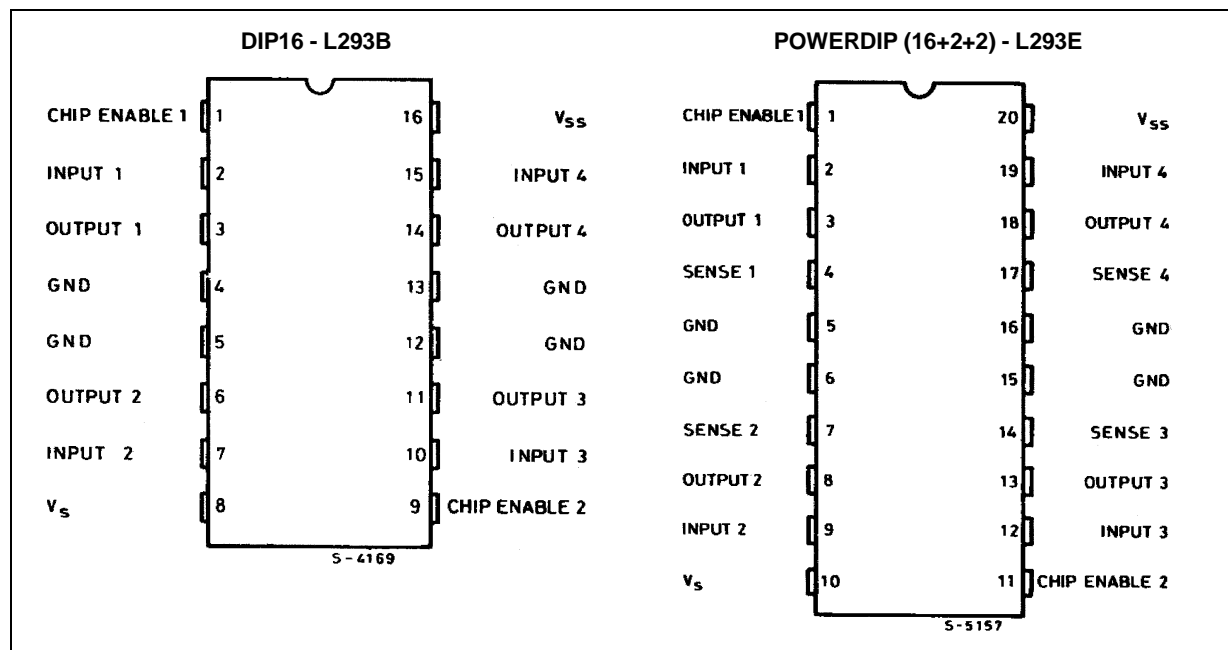
ORDERING NUMBER : L293B



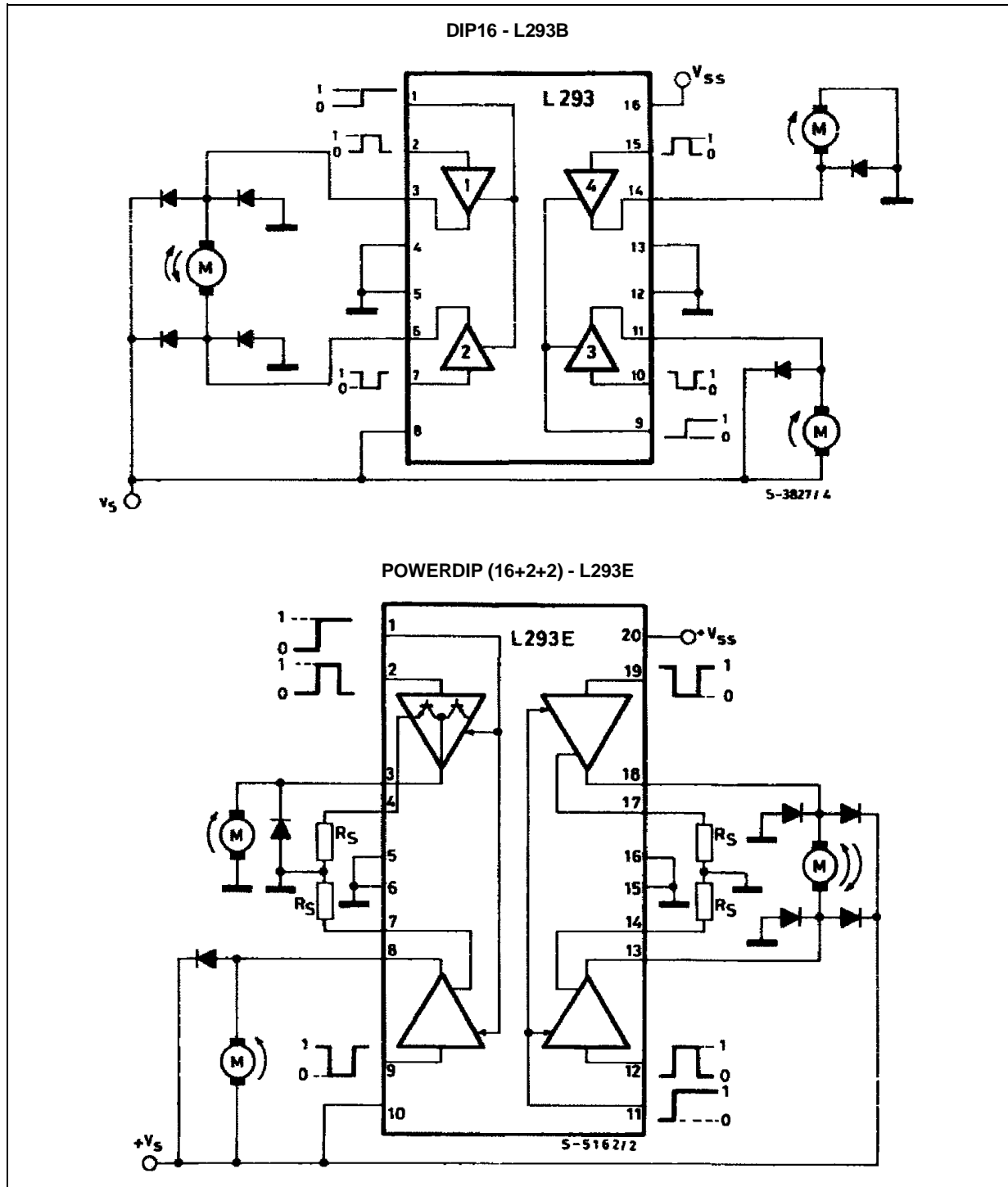
POWERDIP (16 + 2 + 2)

ORDERING NUMBER : L293E

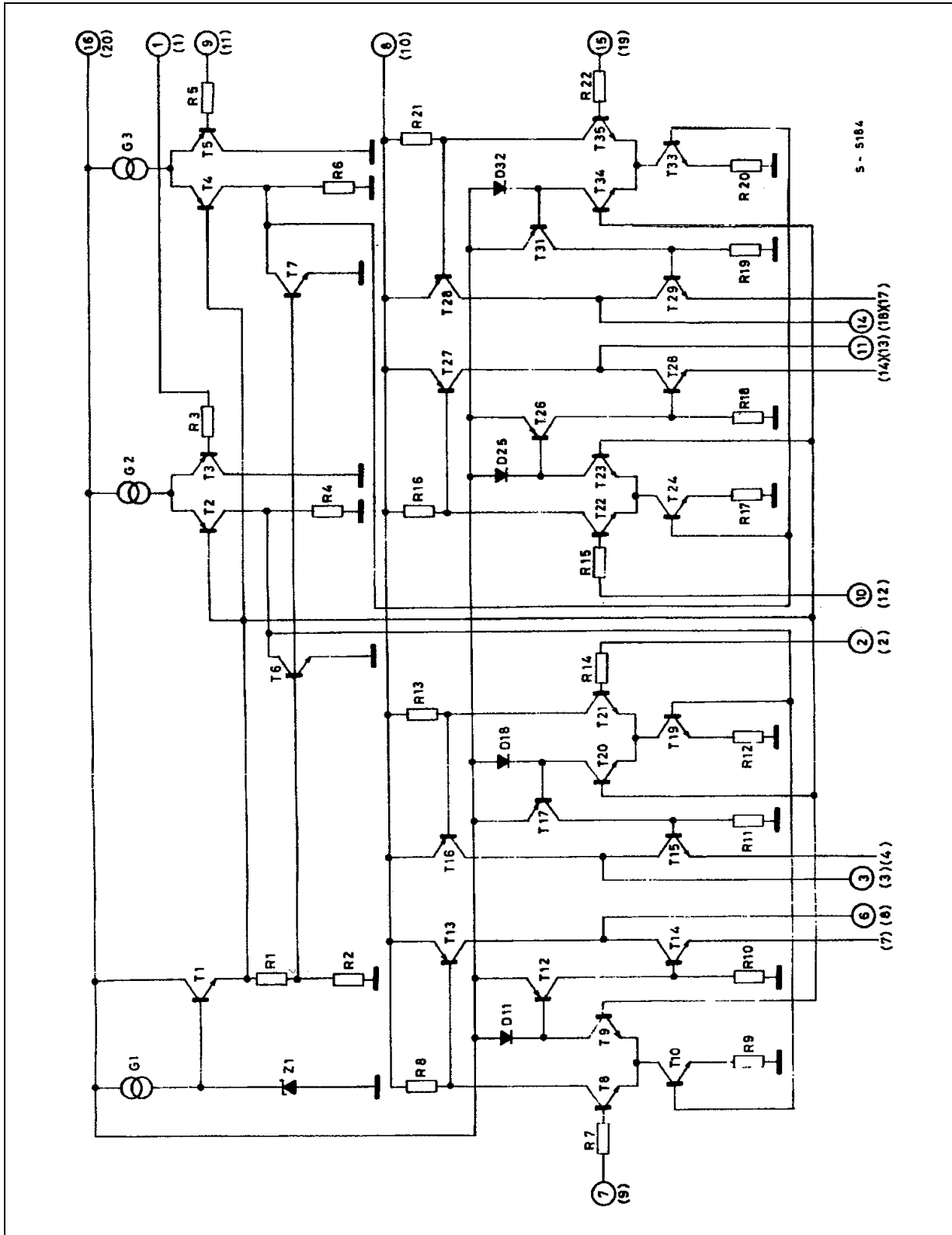
PIN CONNECTIONS



BLOCK DIAGRAMS



SCHEMATIC DIAGRAM



(*) In the L293 these points are not externally available. They are internally connected to the ground (substrate).
 O Pins of L293
 () Pins of L293E.

ABSOLUTE MAXIMUM RATINGS

Symbol	Parameter	Value	Unit
V _s	Supply Voltage	36	V
V _{ss}	Logic Supply Voltage	36	V
V _i	Input Voltage	7	V
V _{inh}	Inhibit Voltage	7	V
I _{out}	Peak Output Current (non repetitive t = 5ms)	2	A
P _{tot}	Total Power Dissipation at T _{ground-pins} = 80°C	5	W
T _{stg} , T _j	Storage and Junction Temperature	-40 to +150	°C

THERMAL DATA

Symbol	Parameter	Value	Unit
R _{th j-case}	Thermal Resistance Junction-case	Max. 14	°C/W
R _{th j-amb}	Thermal Resistance Junction-ambient	Max. 80	°C/W

ELECTRICAL CHARACTERISTICS

For each channel, V_s = 24V, V_{ss} = 5V, T_{amb} = 25°C, unless otherwise specified

Symbol	Parameter	Test Conditions	Min.	TYP.	Max.	Unit
V _s	Supply Voltage		V _{ss}		36	V
V _{ss}	Logic Supply Voltage		4.5		36	V
I _s	Total Quiescent Supply Current	V _i = L I _o = 0 V _{inh} = H V _i = H I _o = 0 V _{inh} = H V _{inh} = L		2 16	6 24 4	mA
I _{ss}	Total Quiescent Logic Supply Current	V _i = L I _o = 0 V _{inh} = H V _i = H I _o = 0 V _{inh} = H V _{inh} = L		44 16 16	60 22 24	mA
V _{iL}	Input Low Voltage		-0.3		1.5	V
V _{iH}	Input High Voltage	V _{ss} ≤ 7V V _{ss} > 7V	2.3 2.3		V _{ss} 7	V
I _{iL}	Low Voltage Input Current	V _{il} = 1.5V			-10	µA
I _{iH}	High Voltage Input Current	2.3V ≤ V _{iH} ≤ V _{ss} - 0.6V		30	100	µA
V _{inhL}	Inhibit Low Voltage		-0.3		1.5	V
V _{inhH}	Inhibit High Voltage	V _{ss} ≤ 7V V _{ss} > 7V	2.3 2.3		V _{ss} 7	V
I _{inhL}	Low Voltage Inhibit Current	V _{inhL} = 1.5V		-30	-100	µA
I _{inhH}	High Voltage Inhibit Current	2.3V ≤ V _{inhH} ≤ V _{ss} - 0.6V			±10	µA
V _{CEsatH}	Source Output Saturation Voltage	I _o = -1A		1.4	1.8	V
V _{CEsatL}	Sink Output Saturation Voltage	I _o = 1A		1.2	1.8	V
V _{SENS}	Sensing Voltage (pins 4, 7, 14, 17) (**)				2	V
t _r	Rise Time	0.1 to 0.9 V _o (*)		250		ns
t _f	Fall Time	0.9 to 0.1 V _o (*)		250		ns
t _{on}	Turn-on Delay	0.5 V _i to 0.5 V _o (*)		750		ns
t _{off}	Turn-off Delay	0.5 V _i to 0.5 V _o (*)		200		ns

* See figure 1
 ** Referred to L293E

TRUTH TABLE

V _i (each channel)	V _o	V _{inh} ^(∞)
H	H	H
L	L	H
H	X ^(*)	L
L	X ^(*)	L

(*) High output impedance
 (**) Relative to the considerate channel

Figure 1 : Switching Timers

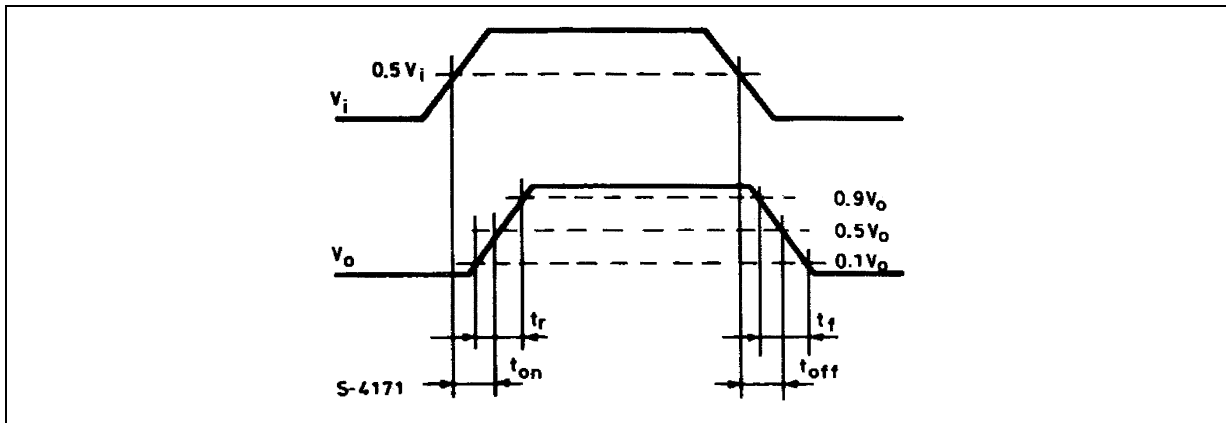


Figure 2 : Saturation voltage versus Output Current

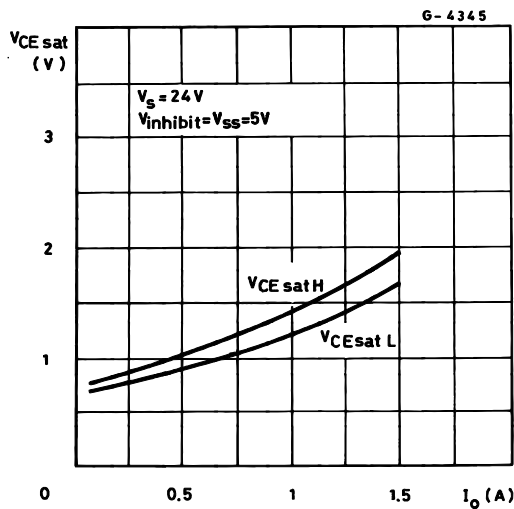


Figure 4 : Sink Saturation Voltage versus Ambient Temperature

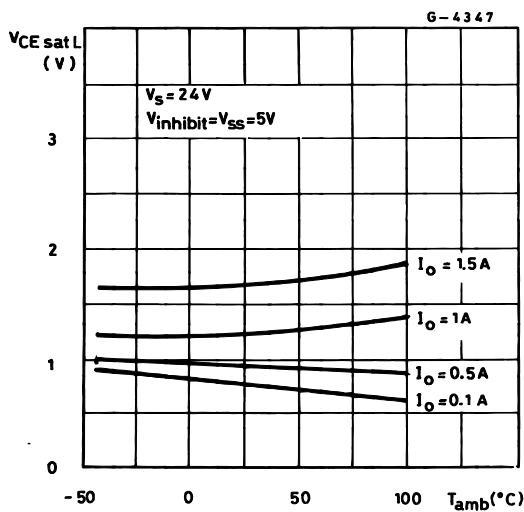


Figure 3 : Source Saturation Voltage versus Ambient Temperature

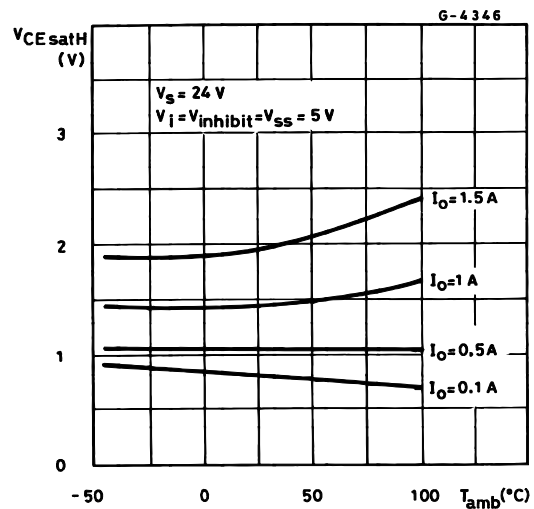


Figure 5 : Quiescent Logic Supply Current versus Logic Supply Voltage

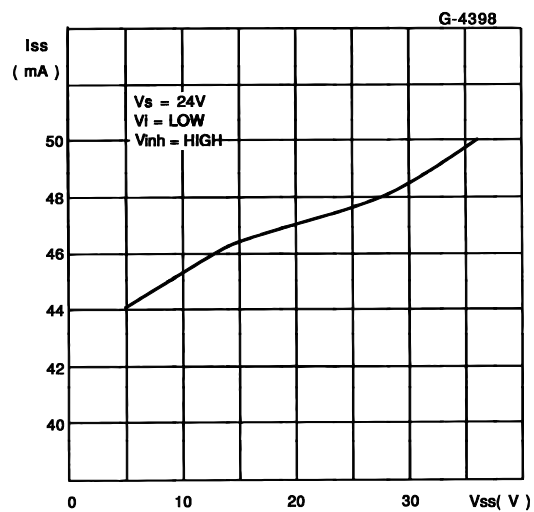


Figure 6 : Output Voltage versus Input Voltage

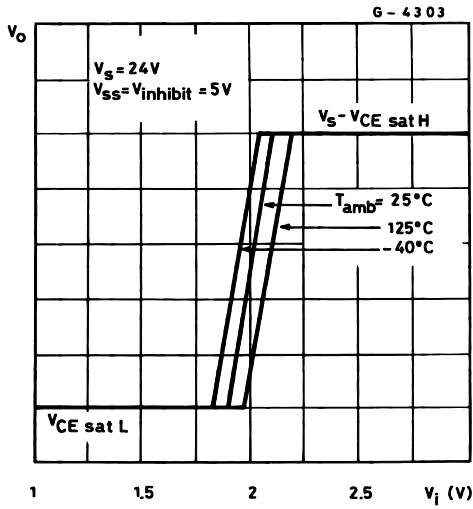
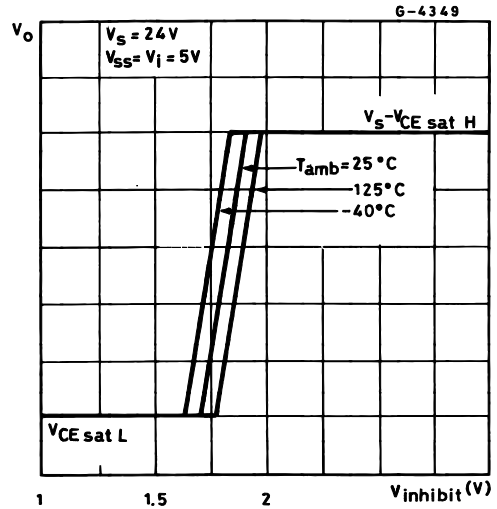
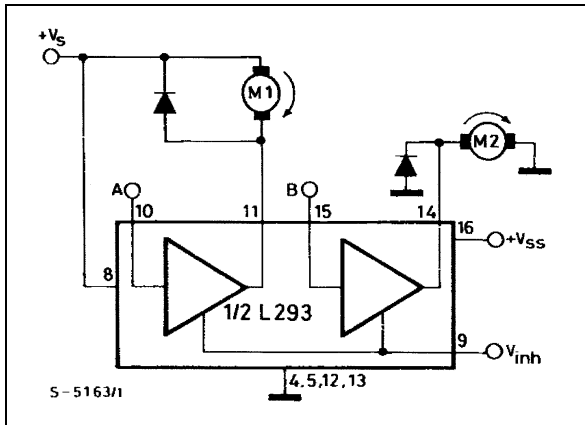


Figure 7 : Output Voltage versus Inhibit Voltage



APPLICATION INFORMATION

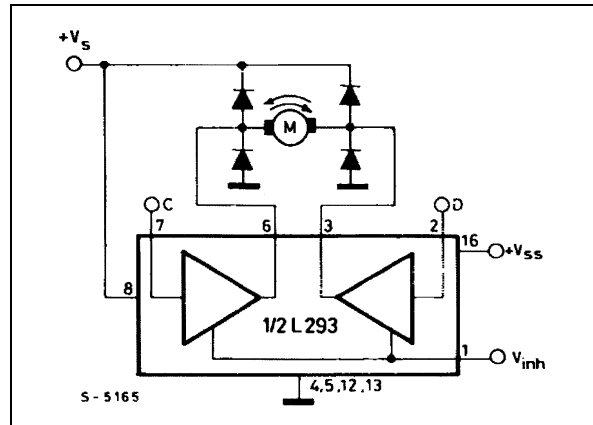
Figure 8 : DC Motor Controls (with connection to ground and to the supply voltage)



V_{inh}	A	M1	B	M2
H	H	Fast Motor Stop	H	Run
H	L	Run	L	Fast Motor Stop
L	X	Free Running Motor Stop	X	Free Running Motor Stop

L = Low H = High X = Don't Care

Figure 9 : Bidirectional DC Motor Control



Inputs	Function	
$V_{inh} = H$	C = H ; D = L	Turn Right
	C = L ; D = H	Turn Left
	C = D	Fast Motor Stop
$V_{inh} = L$	C = X ; D = X	Free Running Motor Stop

L = Low H = High X = Don't Care

Figure 10 : Bipolar Stepping Motor Control

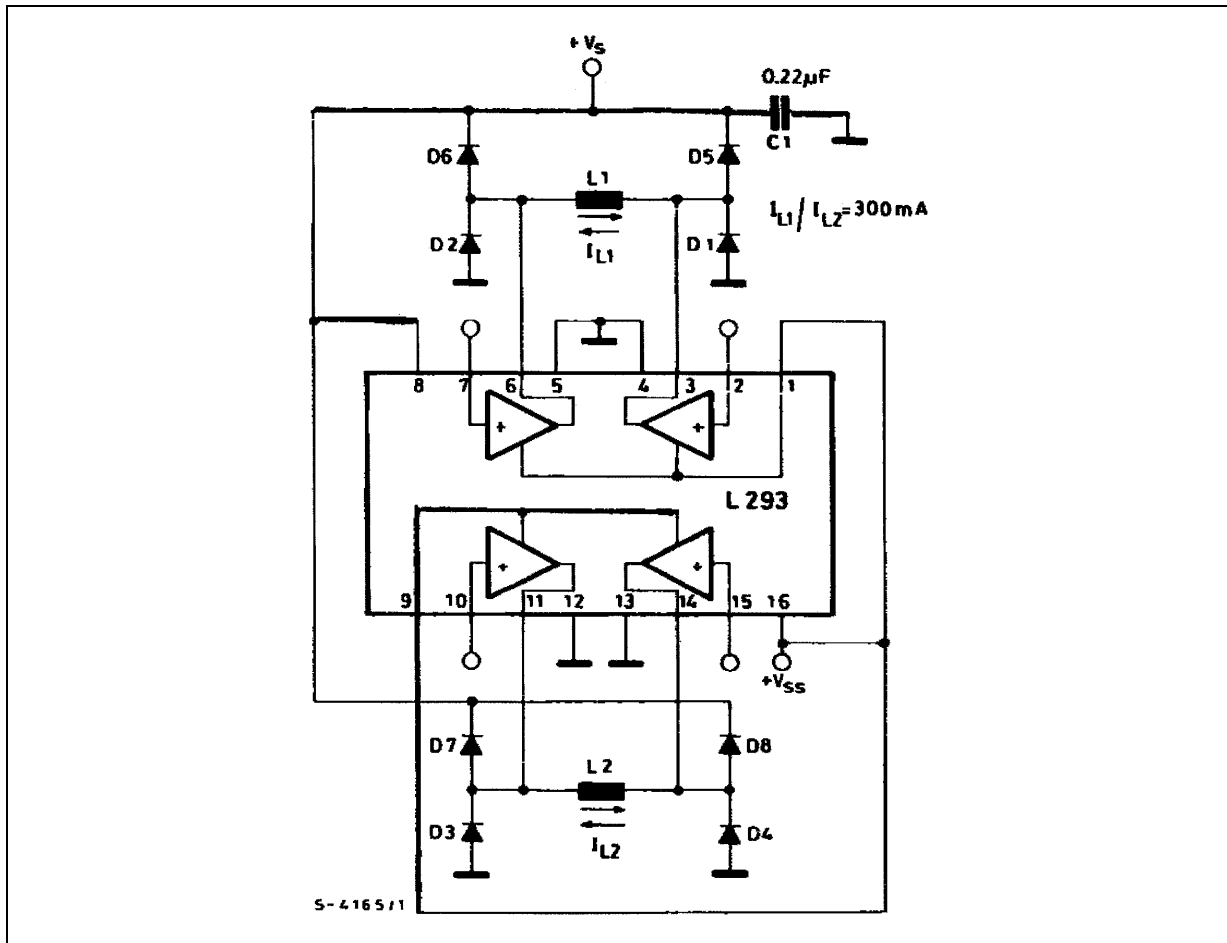
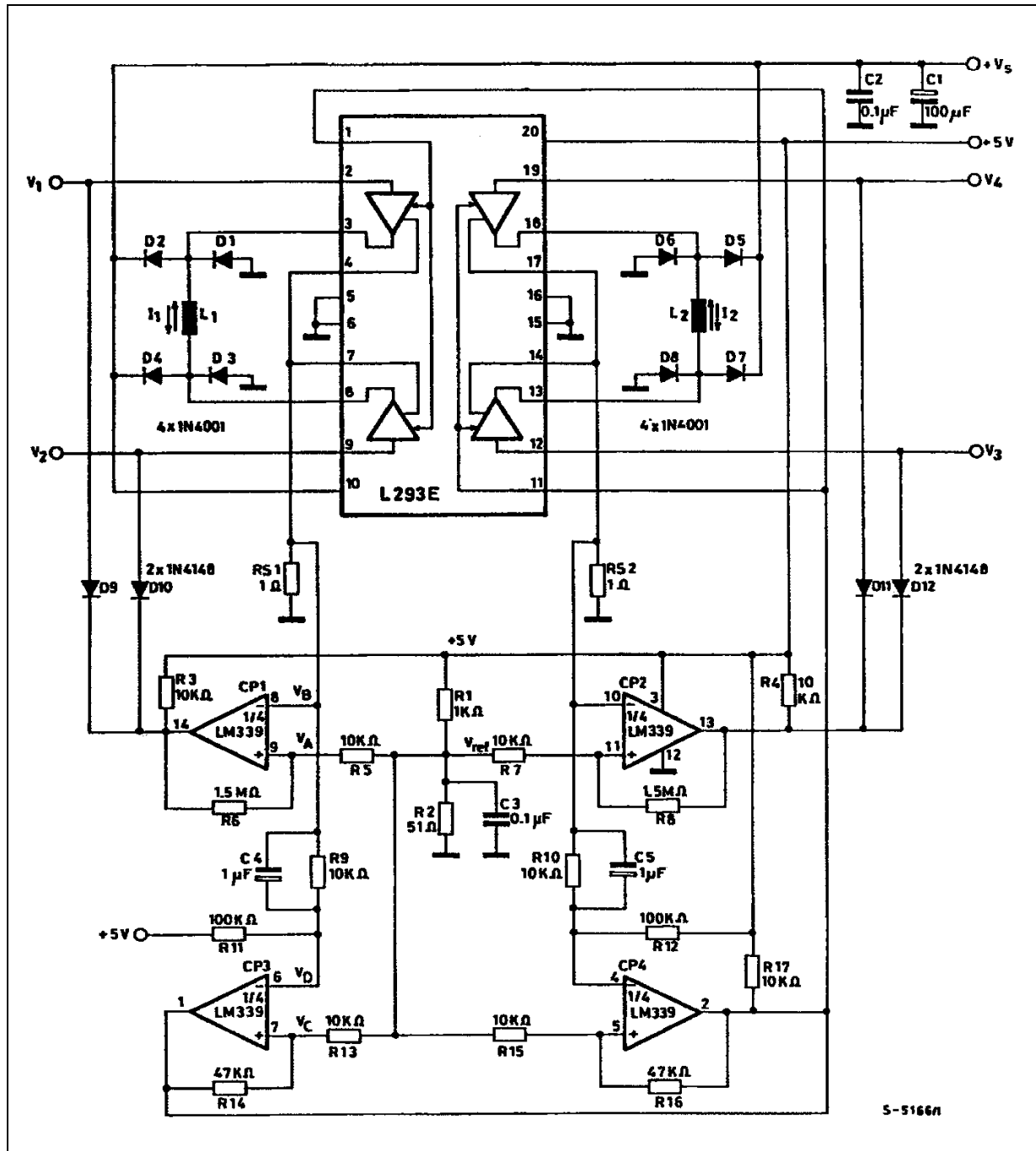


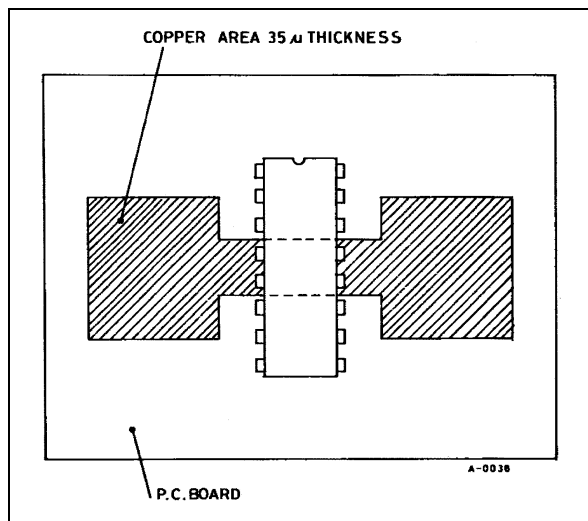
Figure 11 : Stepping Motor Driver with Phase Current Control and Short Circuit Protection



MOUNTING INSTRUCTIONS

The $R_{thj-amb}$ of the L293B and the L293E can be reduced by soldering the GND pins to a suitable copper area of the printed circuit board as shown in figure 12 or to an external heatsink (figure 13).

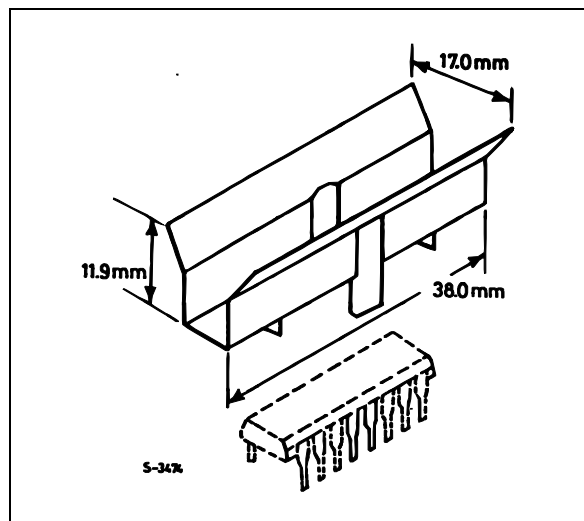
Figure 12 :Example of P.C. Board Copper Area which is Used as Heatsink



During soldering the pins temperature must not exceed 260°C and the soldering time must not be longer than 12 seconds.

The external heatsink or printed circuit copper area must be connected to electrical ground.

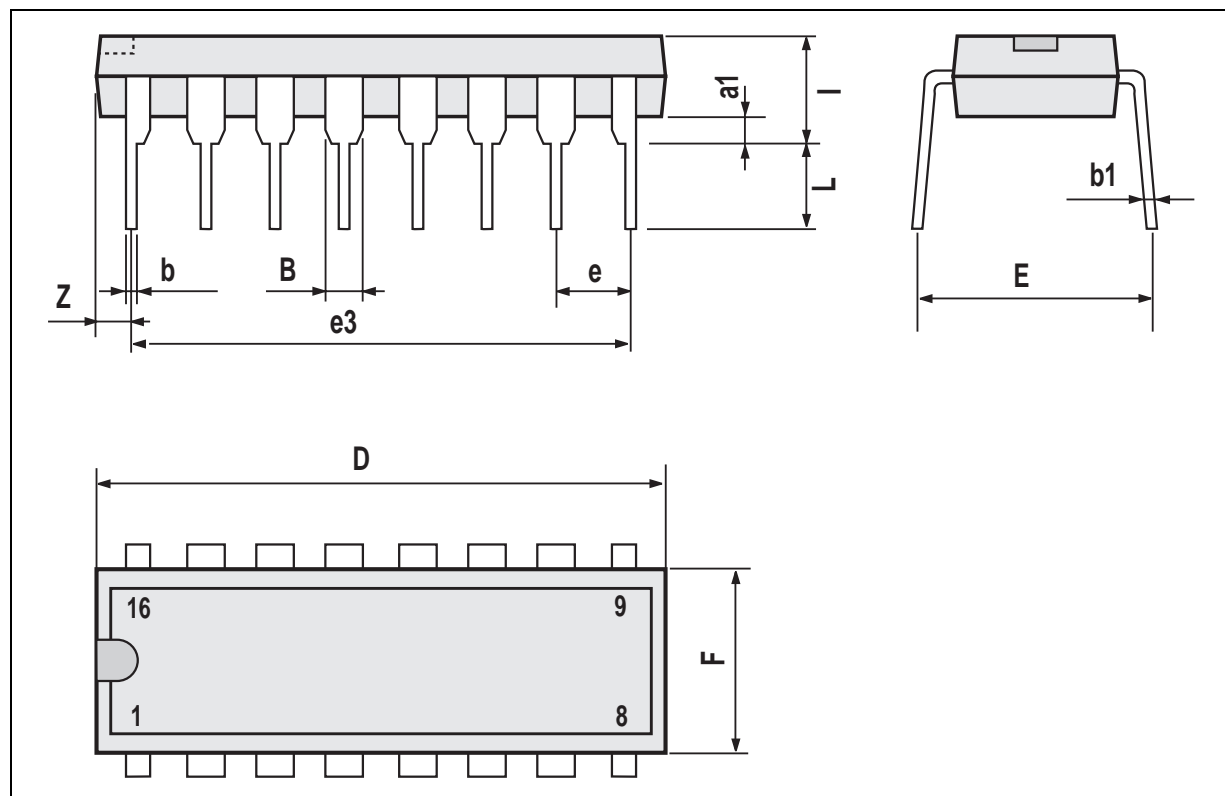
Figure 13 :External Heatsink Mounting Example ($R_{th} = 30^{\circ}\text{C/W}$)



DIP16 PACKAGE MECHANICAL DATA

Dimensions	Millimeters			Inches		
	Min.	Typ.	Max.	Min.	Typ.	Max.
a1	0.51			0.020		
B	0.77		1.65	0.030		0.065
b		0.5			0.020	
b1		0.25			0.010	
D			20			0.787
E		8.5			0.335	
e		2.54			0.100	
e3		17.78			0.700	
F			7.1			0.280
i			5.1			0.201
L		3.3			0.130	
Z			1.27			0.050

DIP16PW/TBL

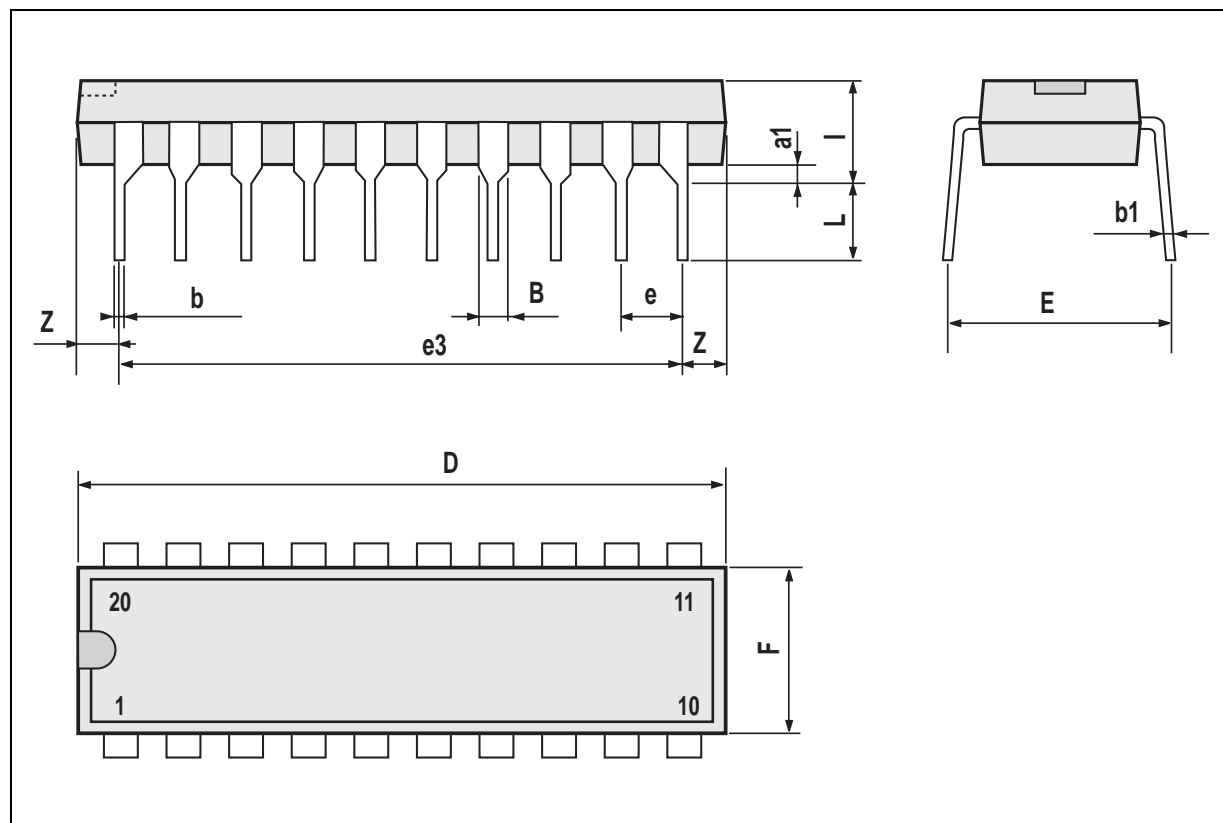


PNDIP16W/EP5

POWERDIP (16+2+2) PACKAGE MECHANICAL DATA

Dimensions	Millimeters			Inches		
	Min.	Typ.	Max.	Min.	Typ.	Max.
a1	0.51			0.020		
B	0.85		1.4	0.033		0.055
b		0.5			0.020	
b1	0.38		0.5	0.015		0.020
D			24.8			0.976
E		8.8			0.346	
e		2.54			0.100	
e3		22.86			0.900	
F			7.1			0.280
i			5.1			0.201
L		3.3			0.130	
Z			1.27			0.050

DIP20/PW.TBL



PMDIP20WEPS

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